# Energy reconstruction with machine learning techniques in JUNO: aggregated features approach

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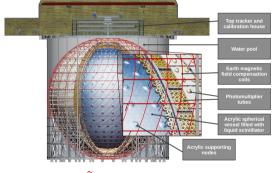


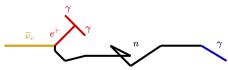




# Introduction to the JUNO experiment

- Jiangmen Underground Neutrino Observatory:
  - multipurpose experiment
  - 53 km away from 8 reactor cores in China
  - data taking expected in  $\sim$ 2023
  - JUNO Collaboration:
    - 77 institutions
    - 697 collaborators
- The main goals of JUNO:
  - neutrino mass ordering ( $3\sigma$  in 6 years)
  - precise measure of oscillation parameters  $\sin^2 \theta_{12}$ ,  $\Delta m_{21}^2$ ,  $\Delta m_{31}^2$
- The Central Detector:
  - detection channel:  $\overline{\nu}_e + p \rightarrow e^+ + n$ ;
  - deposited energy converts to optical light
  - the largest liquid scintillator detector: 20 kt
  - 77.9% photo-coverage: 18k 20", 26k 3" photo-multiplier tubes (PMTs)



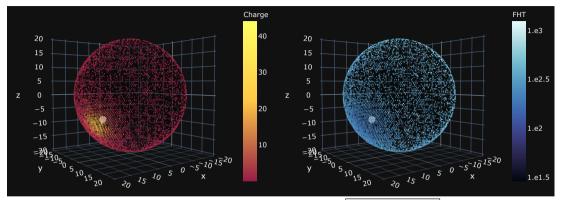


## Machine Learning (ML) in HEP

- ML methods are used at all levels of data processing in many HEP experiments:
  - signal/background discrimination
  - event selection in the trigger
  - event simulation
  - anomaly detection
  - identification, etc.
- Why is ML useful for HEP?
  - Faster. More precisely, with proper training
  - **Adequate** for many purposes simultaneously: event simulation, analysis, reconstruction, identification, etc.
  - GPU friendly by construction, which is important for big data processing
- Machine-learning algorithms use statistics to find patterns in massive amounts of data
- Our task is a supervised learning problem (regression)

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## Problem statement



An example of a positron event with deposited energy  $\sim\!\!6$  MeV. The grey sphere — the primary vertex.

Charge at PMT

First Hit Time (FHT) at PMT

#### We want to reconstruct:

Deposited energy  $E_{\text{dep}}$  with resolution 3% @ 1 MeV

## **Datasets**

- Two datasets: for training and for testing
- generated by the Monte Carlo method

- full detector and electronics simulation
- using the official JUNO software

## Data description:

- positron events
- uniformly spread in the volume of the central detector
- ullet  $E_{
  m kin} \in [0,10]$  MeV.  $E_{
  m dep} = E_{
  m kin} + 1.022$  MeV
- Training dataset:
  - 5 million events
  - $oldsymbol{\circ}$  uniformly distributed in kinetic energy  $E_{
    m kin}$

## Testing dataset:

- subsets with discrete kinetic energies:
- **1** 0, 0.1, 0.3, 0.6, 1, 2, ..., 10 [MeV]
- **5**  $\sum = 1.4$  **million** events: each subset contains 100k

# Aggregated features

We use aggregated information from the whole array of PMTs as features for models:

- AccumCharge the accumulated charge on fired PMTs
- nPMTs the total number of fired PMTs
- 3 Coordinates of the center of charge:

$$(x_{ ext{cc}},\ y_{ ext{cc}},\ z_{ ext{cc}}) = \vec{r}_{ ext{cc}} = rac{\sum_{i=1}^{N_{ ext{PMTs}}} \vec{r}_{ ext{PMT}_i} \cdot n_{ ext{p.e.},i}}{\sum_{i=1}^{N_{ ext{PMTs}}} n_{ ext{p.e.},i}}$$

and its radial component:  $R_{\rm cc} = |\vec{r}_{\rm cc}|$ 

Coordinates of the center of FHT:

$$(x_{
m cht},\ y_{
m cht},\ z_{
m cht}) = ec{r}_{
m cht} = rac{1}{\sum_{i=1}^{N_{
m PMTs}}rac{1}{t_{
m ht,}i+c}} \sum_{i=1}^{N_{
m PMT}i}rac{ec{r}_{
m PMT_i}}{t_{
m ht,}i+c},$$

and its radial component:  $R_{\rm cht} = |\vec{r}_{\rm cht}|$ 

$$\theta_{\rm cc} = \arctan \frac{\sqrt{x_{\rm cc}^2 + y_{\rm cc}^2}}{z_{\rm cc}}$$

with 7 similar features for the components of the center of FHT

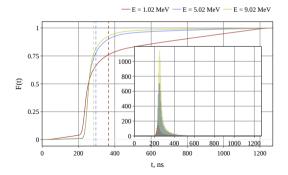


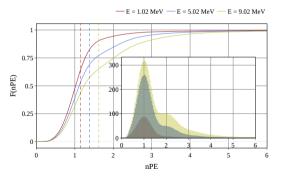
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# Aggregated features

- Percentiles of FHT and charge distributions:
  - {ht<sub>2%</sub>, ht<sub>5%</sub>, ht<sub>10%</sub>, ht<sub>15%</sub>, ..., ht<sub>90%</sub>, ht<sub>95%</sub>}
  - $\bullet \ \{pe_{2\%}, pe_{5\%}, pe_{10\%}, pe_{15\%}, ..., pe_{90\%}, pe_{95\%}\}$

- Differences between percentiles for FHT:
  - {ht<sub>5%-2%</sub>, ht<sub>10%-5%</sub>, ..., ht<sub>95%-90%</sub>}
- Moments for FHT and charge distributions:
  - $\{ht_{mean}, ht_{std}, ht_{skew}, ht_{kurtosis}\}$
  - $\bullet \ \{pe_{mean}, pe_{std}, pe_{skew}, pe_{kurtosis}\}$





CDFs and PDFs for FHT (left) and charge (right) distributions.  $R \simeq 0$  m,  $E_{\rm kin}$  varied. Dashes lines show mean values,

# Models description: BDT

A Decision Tree (DT) takes a set of input features and splits input data recursively based on those features.

#### **Boosted Decision Trees (BDT):**

- Ensemble model
- DT as base algorithm
- DTs in BDT are trained sequentially
- Each subsequent DT is trained to correct errors of previous DTs in the ensemble

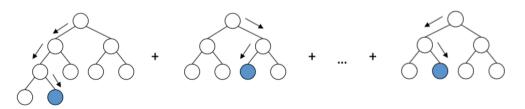


Figure: BDT demonstration. Source: https://arogozhnikov.github.io/

# BDT: hyperparameters and benefits

#### Main tunable hyperparameters:

- **Max. depth**: The maximum depth of a tree (usually <12)
- ullet Learning rate: This determines the impact of each tree on the final outcome (usually pprox 0.1)
- **Number of trees**: How many trees in ensemble

#### **Benefits**:

- Fast for training and prediction
- Easier to tune
- Minimalistic

# BDT: optimized set of features

#### BDT from XGBoost:

• Optimized **set of features** (sorted by *importance*):

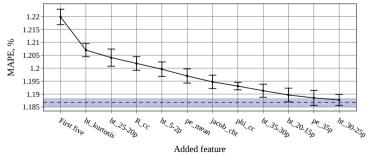
- AccumCharge
- $R_{\rm cht}$
- $pe_{std}$

- nPMTs
- $ht_{kurtosis}$
- $ht_{25\%-20\%}$
- $R_{cc}$

- ht<sub>5%-2%</sub>
- pemean
- $J_{\rm cht}$
- $\phi_{cc}$

- $ht_{35\%-30\%}$
- $ht_{20\%-15\%}$
- pe₃₅
   pe₃ѕ
   peъ
- $ht_{30\%-25\%}$
- Optimized hyperparameters (using Grid Search):
  - The maximum depth of the tree: 10
  - Number of trees in the ensemble:  $\sim$ 500
  - **1** Learning rate: 0.08

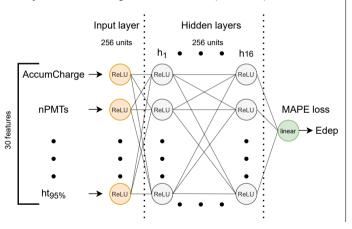
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# Models description: FCDNN

Fully-connected deep neural network (**FCDNN**):



- The search for hyperparameters was performed using *BayesianOptimizer*
- Training with early stopping
- Validation dataset: 400k events
- *Selected features* provided the same performance as full set:
  - AccumCharge
- $\rho_{\rm cht}$

2 nPMTs
3 R<sub>cc</sub>

o pe<sub>mean</sub>

 $egin{array}{cc} egin{array}{cc} B_{
m cht} \end{array}$ 

pe<sub>std</sub>

 $\rho_{cc}$ 

- pe<sub>skew</sub>
  pe<sub>kurtosis</sub>
- Percentiles of FHT distribution: {ht<sub>2%</sub>, ht<sub>5%</sub>, ht<sub>10%</sub>, ht<sub>15%</sub>, ..., ht<sub>90%</sub>, ht<sub>95%</sub>}

#### **Metrics**:

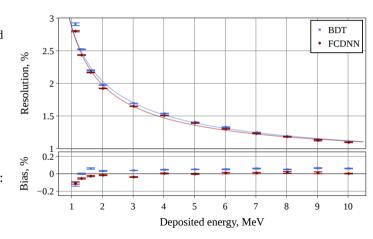
- Defined by a Gaussian fit of the  $E_{\text{predicted}} E_{\text{dep}}$  distributions
- <u>Resolution</u>:  $\sigma/E_{\text{dep}}$ , where  $\sigma$  standard deviation of the fit
- Bias  $\mu/E_{\rm dep}$ , where  $\mu$  mean of the fit

#### Parameterization:

$$\frac{\sigma}{E_{\rm dep}} = \sqrt{\left(\frac{a}{\sqrt{E_{\rm dep}}}\right)^2 + b^2 + \left(\frac{c}{E_{\rm dep}}\right)^2}$$

### Models' pred. time and memory usage:

	BDT	FCDNN
Pred. time, sec/100k	3.5	17
Size, MB	50	12



# Summary

- Energy reconstruction using the information collected by PMTs
- *Aggregated* features approach
- The following ML models are used: **BDT, FCDNN**
- As a result *achieved*:
  - High **quality** 3% @ 1 MeV, requared for physics goals of JUNO
  - ② Great **computation speed**, thanks to a small set of aggregated features (in  $10^4 10^5$  times faster than traditional methods)

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## References and more details

#### **Publications:**

- **A. Gavrikov**, et al. arXiv: 2206.09040 (2022)
- **A. Gavrikov**, et al. EPJ Web Conf. 251 (2021), 03014
- Z. Qian, et al. NIM-A 1010 (2021), 165527

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